

# Artificial Neural Networks for Emissions Modeling and Environmental Routing for Light-Duty Passenger Vehicles

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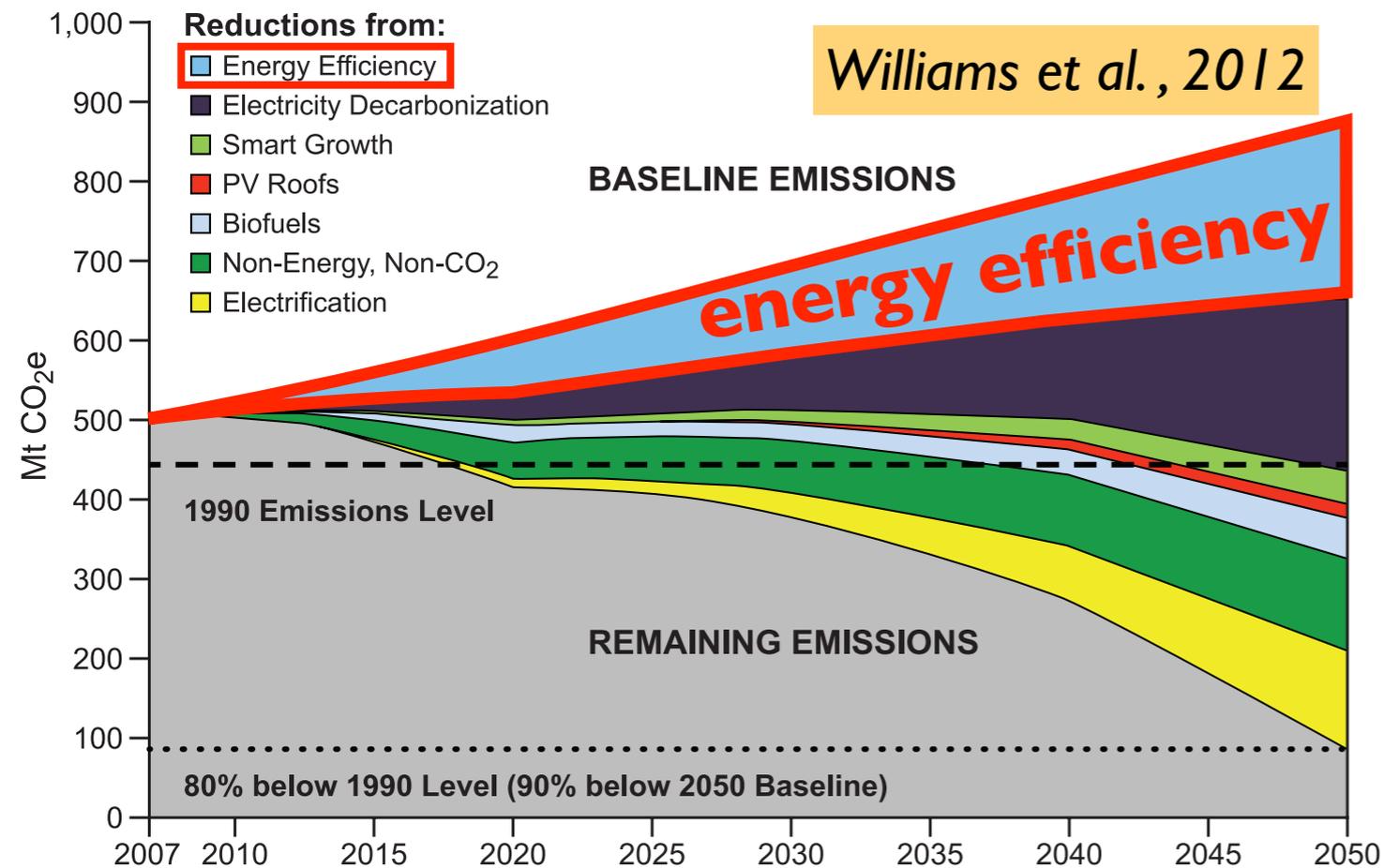
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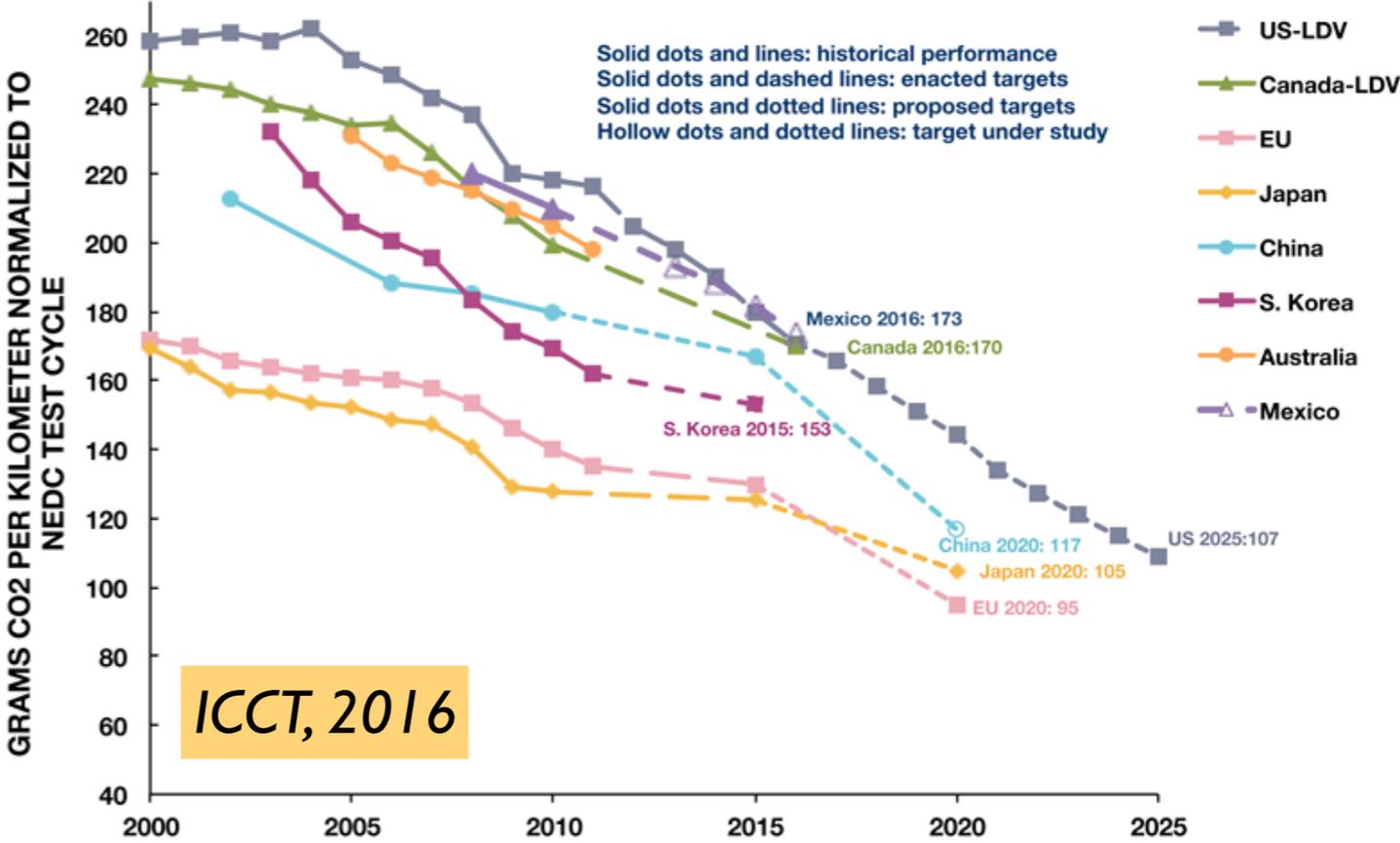
Lightning  
Systems

Williams et al., 2012



❖ Future Reduction in CO<sub>2e</sub> emissions depends on improvements in energy efficiency (e.g., California)

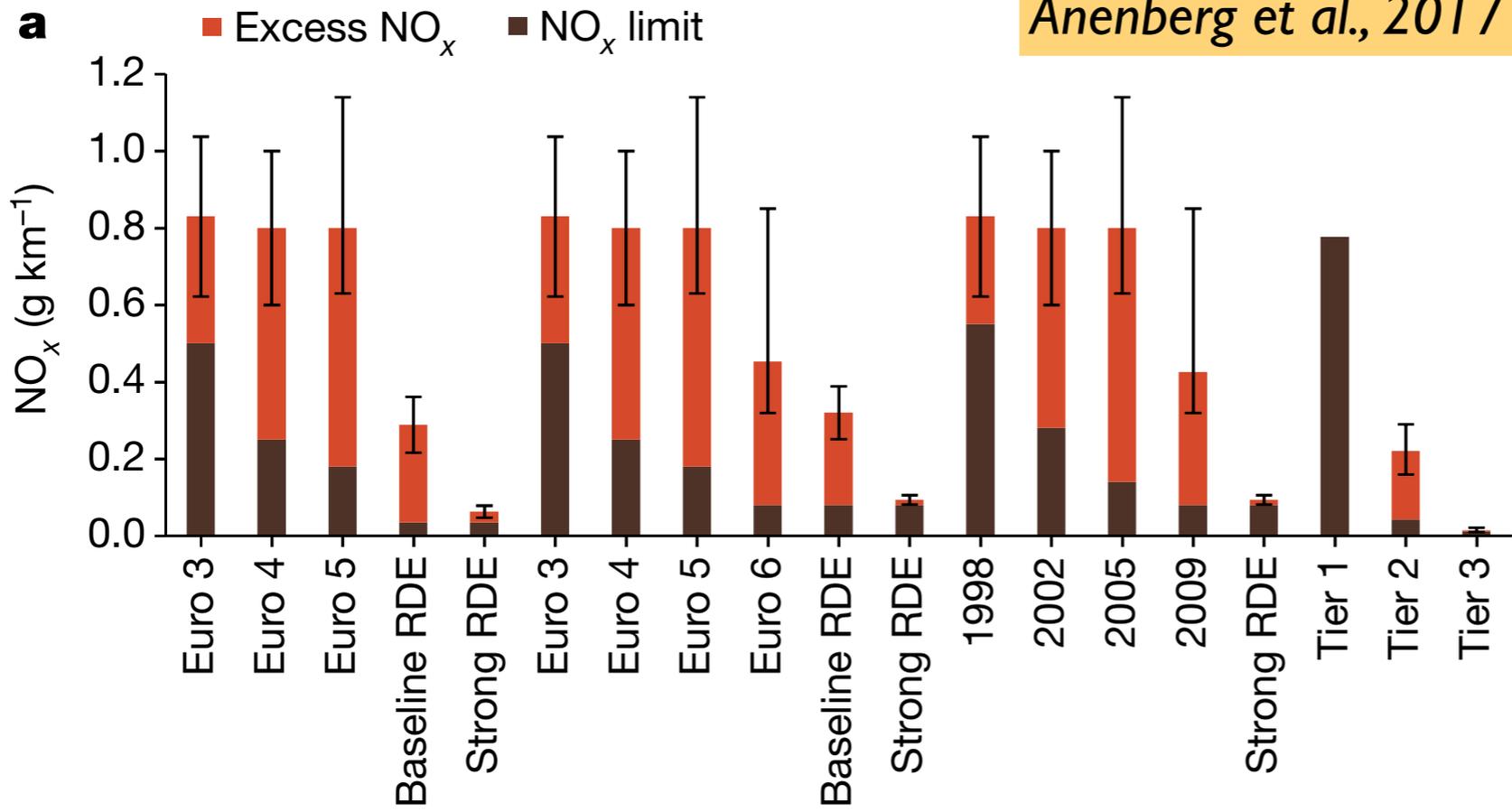
❖ Enacted targets (e.g., **CAFE**) intend to nearly double fuel economy and halve CO<sub>2e</sub> in the United States by 2025



ICCT, 2016

[1] China's target reflects gasoline vehicles only. The target may be lower after new energy vehicles are considered.  
 [2] US, Canada, and Mexico light-duty vehicles include light-commercial vehicles.

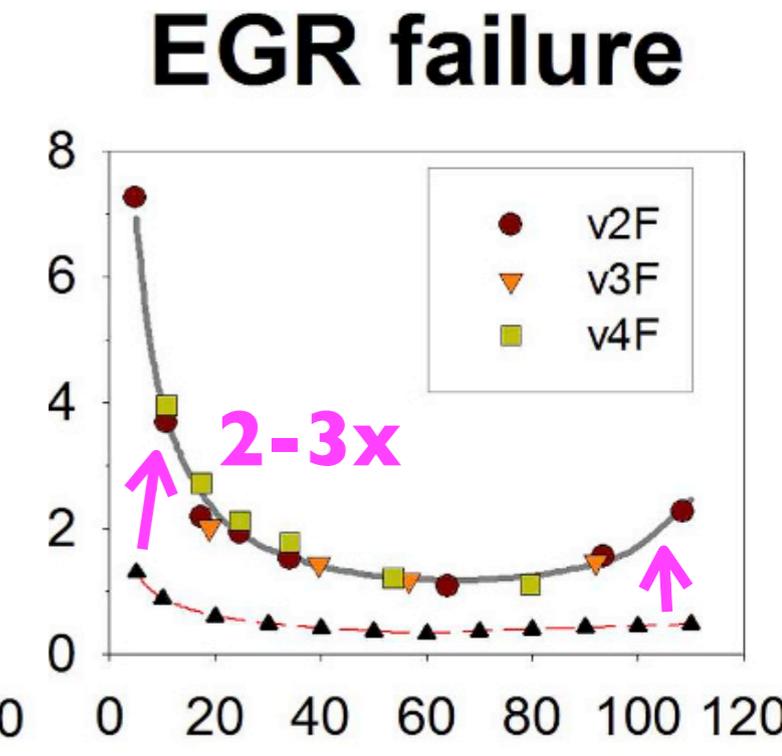
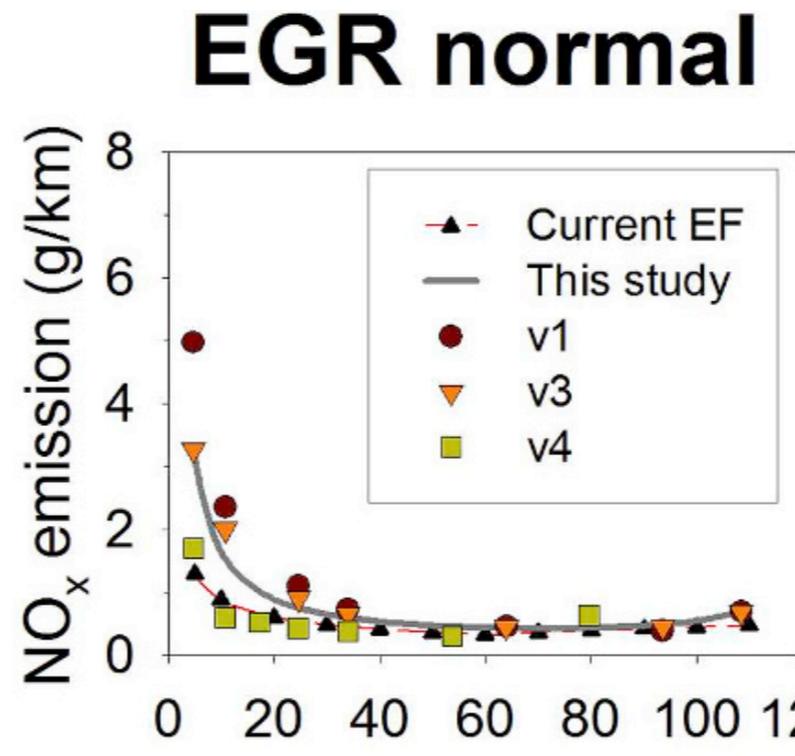
Anenberg et al., 2017



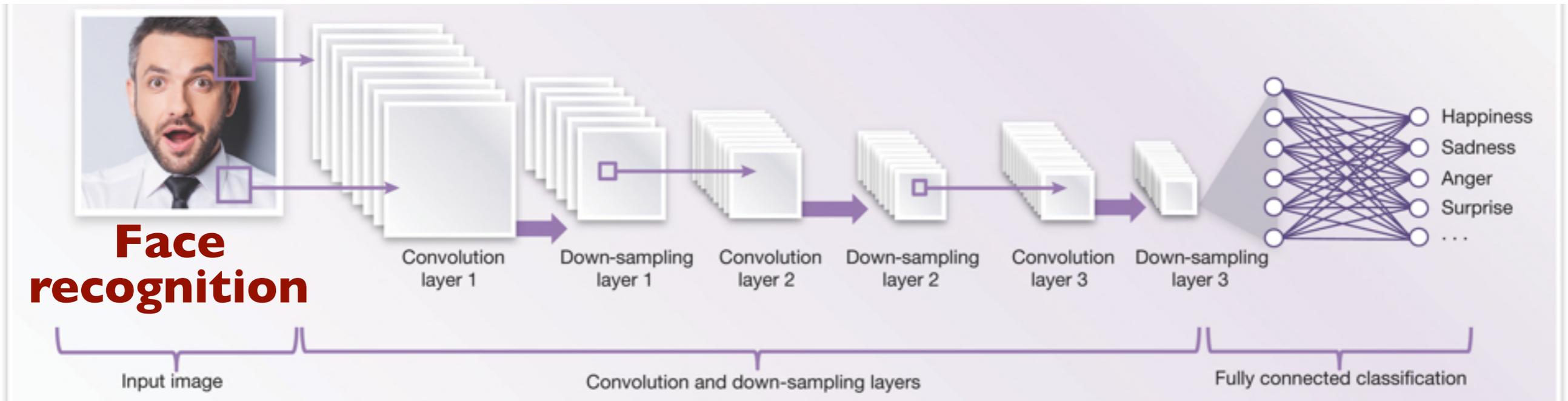
❖ On-road emissions have been found to **exceed standards and dynamometer emissions** (e.g., NO<sub>x</sub>)

Lee et al., 2018

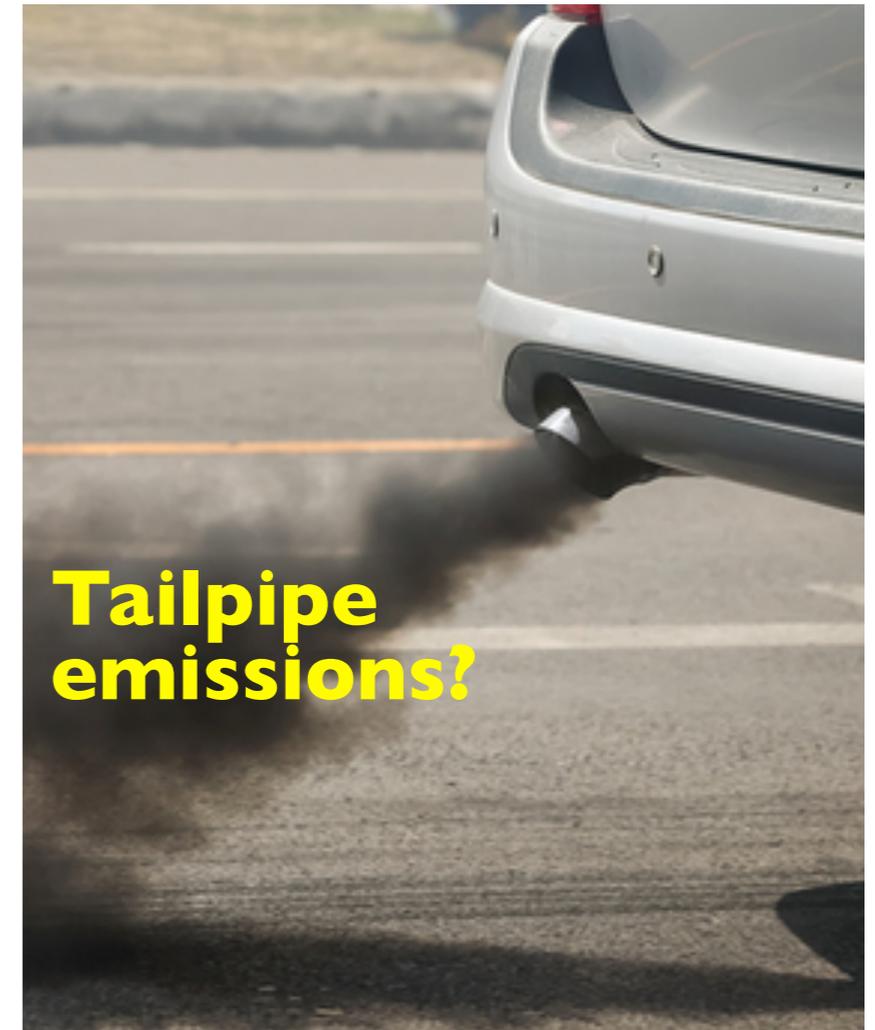
❖ Emissions models (e.g., MOVES, EMFAC), trained on dynamometer tests, **may underestimate on-road emissions**



# Artificial Neural Networks



**Self-driving cars**



**Tailpipe emissions?**

**❖ Goal: Model and evaluate the fuel consumption and tailpipe emissions from light-duty vehicles using artificial neural network (ANN) models**

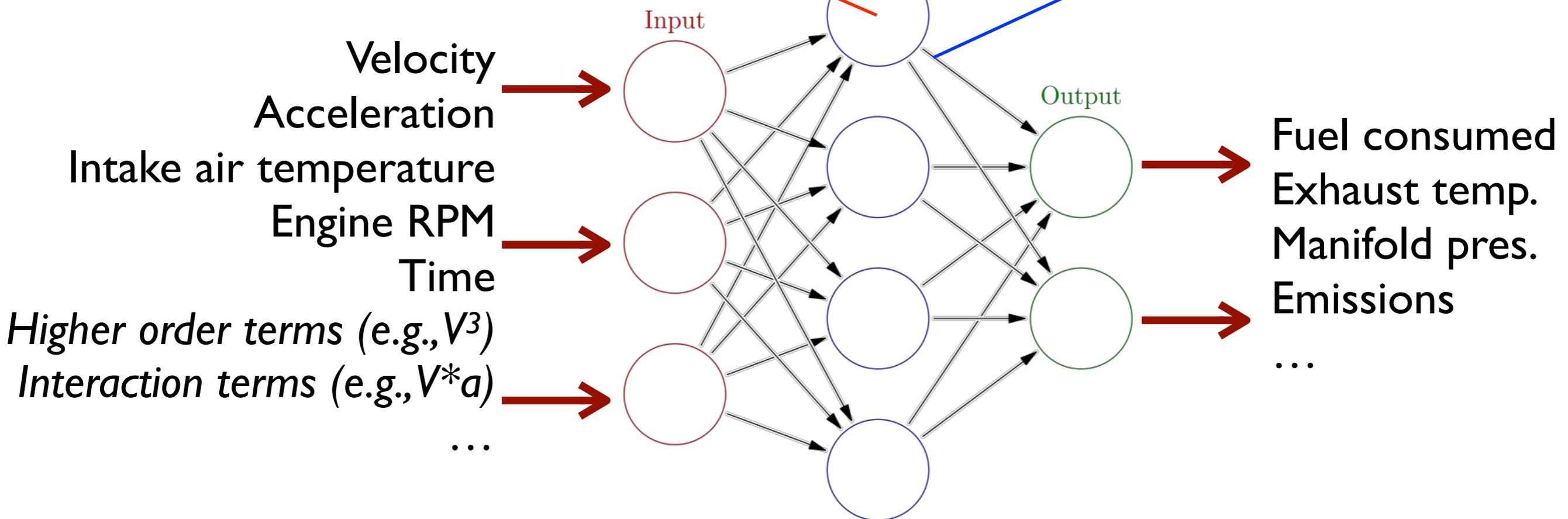
❖ Research questions:

- i. How do you train and test ANNs to model fuel consumption and tailpipe emissions?
- ii. Does the ANN performance vary by pollutant and how do ANNs compare to standard regression models?
- iii. How can ANNs be used for to improve on-road fuel economy?

- ❖ Artificial neural networks (ANNs) are mathematical models used for forecasting that allow complex nonlinear relationships between the input (i.e., predictors) and output (i.e., response) variables

$$z_j = b_j + \sum_{i=1}^4 w_{i,j} x_i$$

$$s(z) = \frac{1}{1 + e^{-z}}$$



*e.g., multi-layer feed-forward network*



❖ **Subaru Impreza gasoline '08**

- 88,000 miles
- Certified as LEV-II
- Emissions control = 3-way cat.



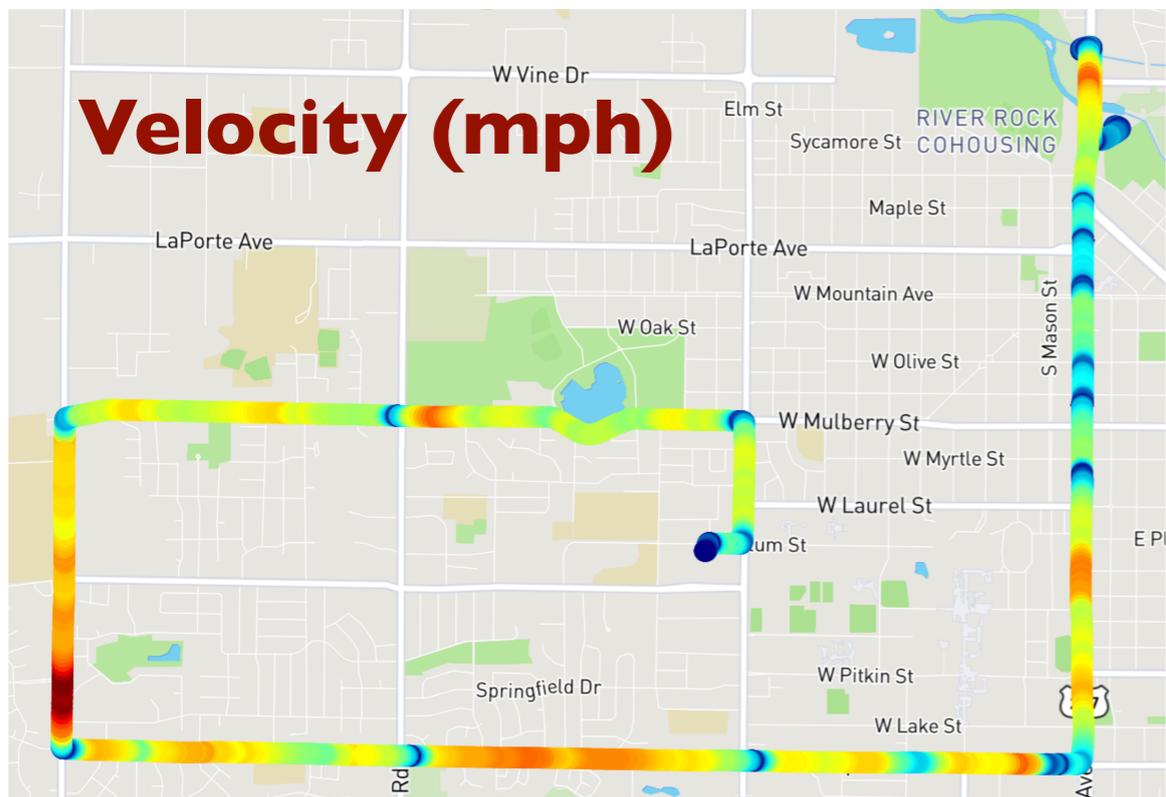
❖ **VW Jetta diesel '03**

- 120,000 miles
- Certified as LEV-I
- Emissions control = EGR

❖ **PEMS: Global MRV AxionR/S+**

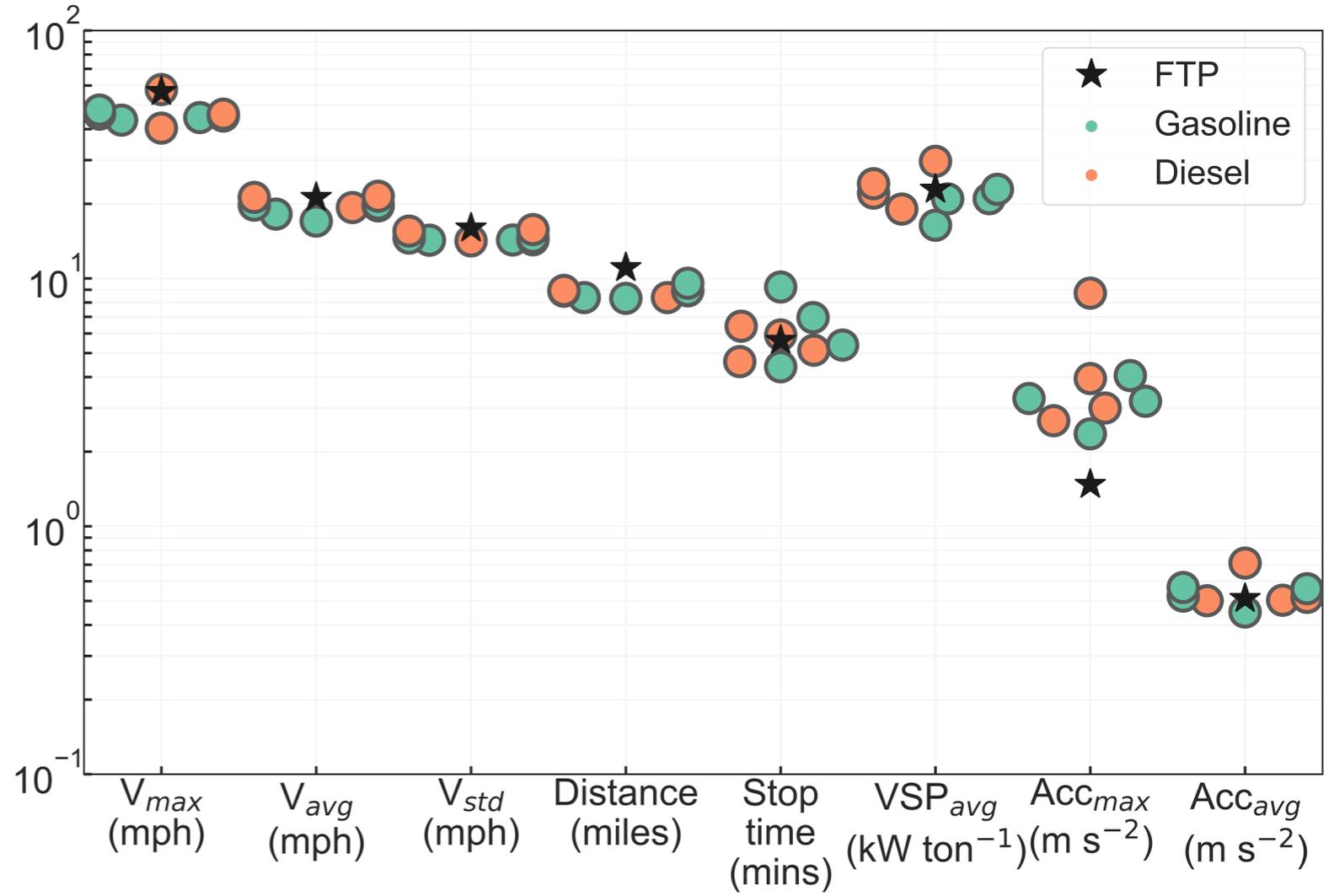
- Measures CO<sub>2</sub>, CO, and HC via NDIR
- Measures NO<sub>x</sub> and O<sub>2</sub> via e-chem
- Measures PM via light scattering
- Connects to and records OBD-II data
- All data streams logged at 1 Hz





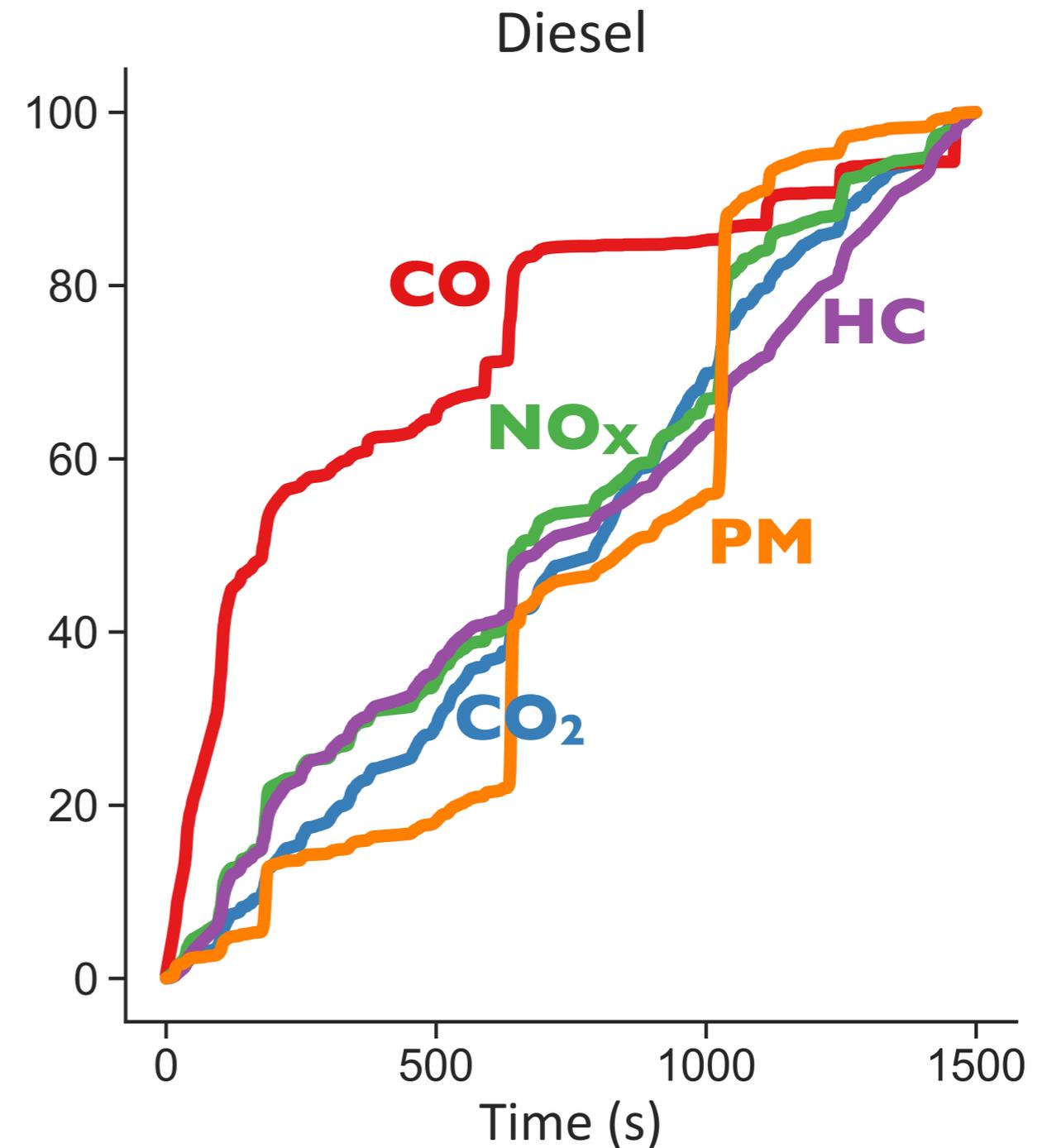
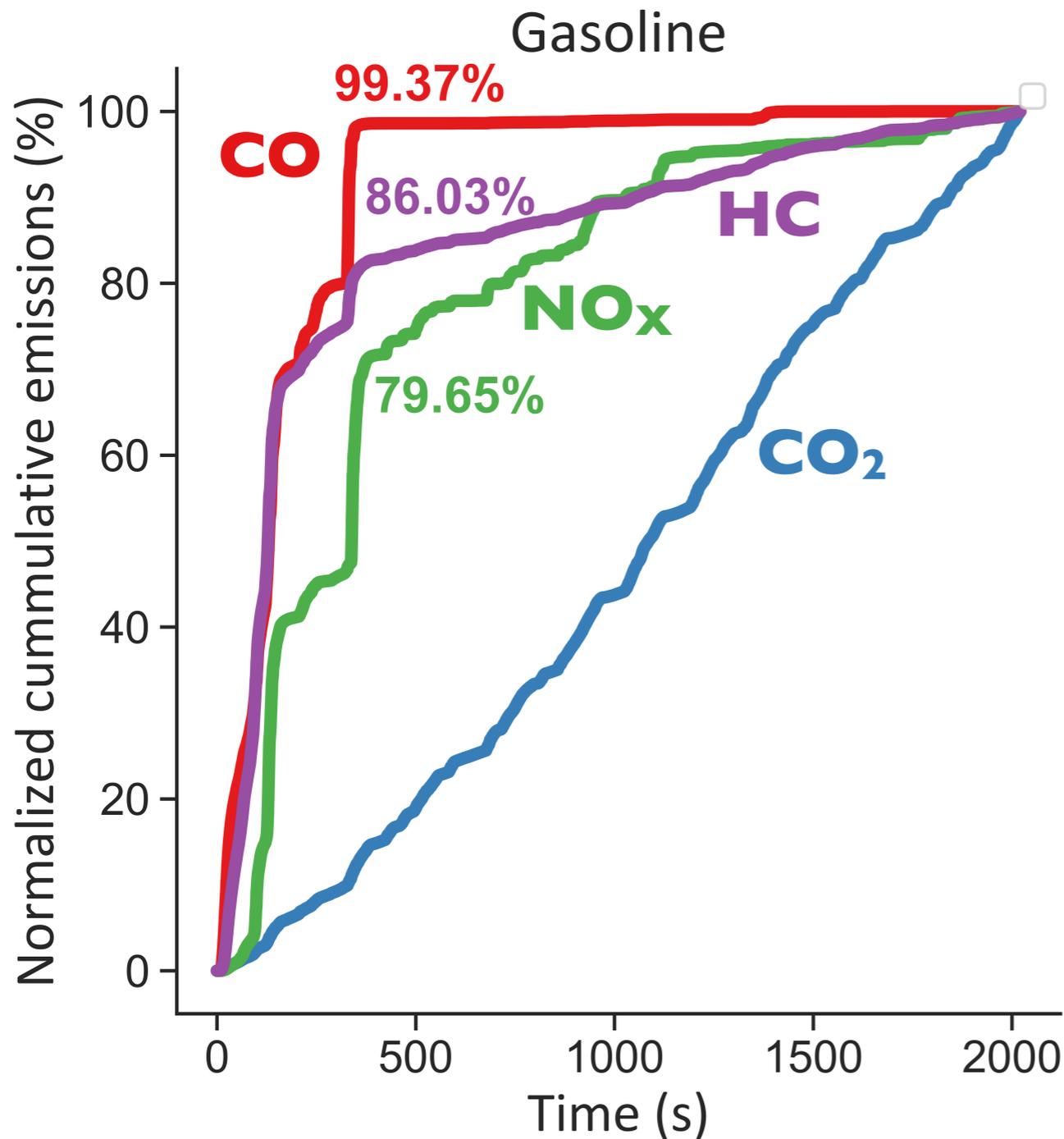
- ❖ ~10 mile urban route in Fort Collins, Colorado (population ~160,000)
- ❖ 4 experiment days each for each vehicle (Spring 2018)

❖ **Route metrics (e.g.,  $V$ ,  $VSP$ ) were consistent with an FTP-75 cycle**

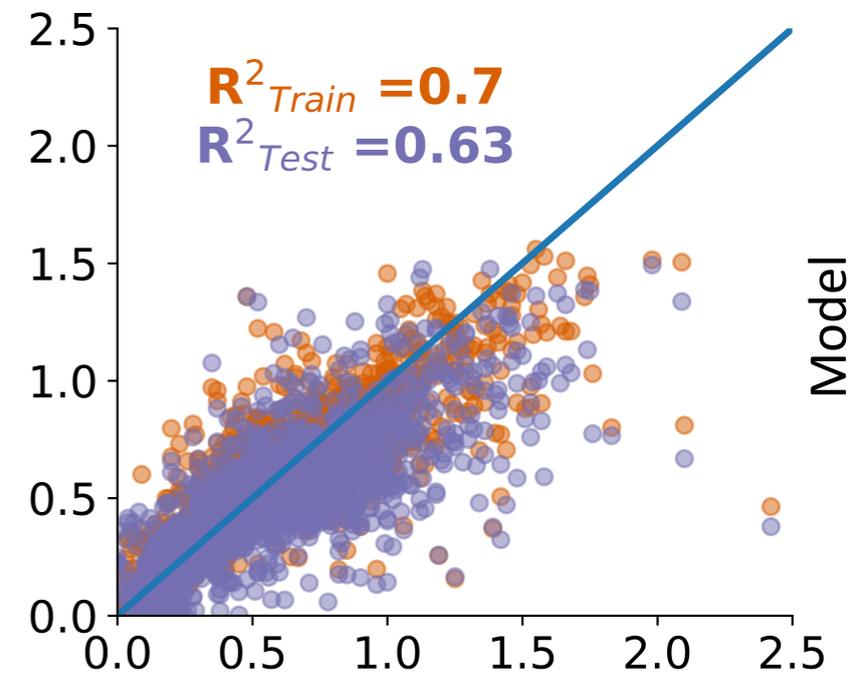
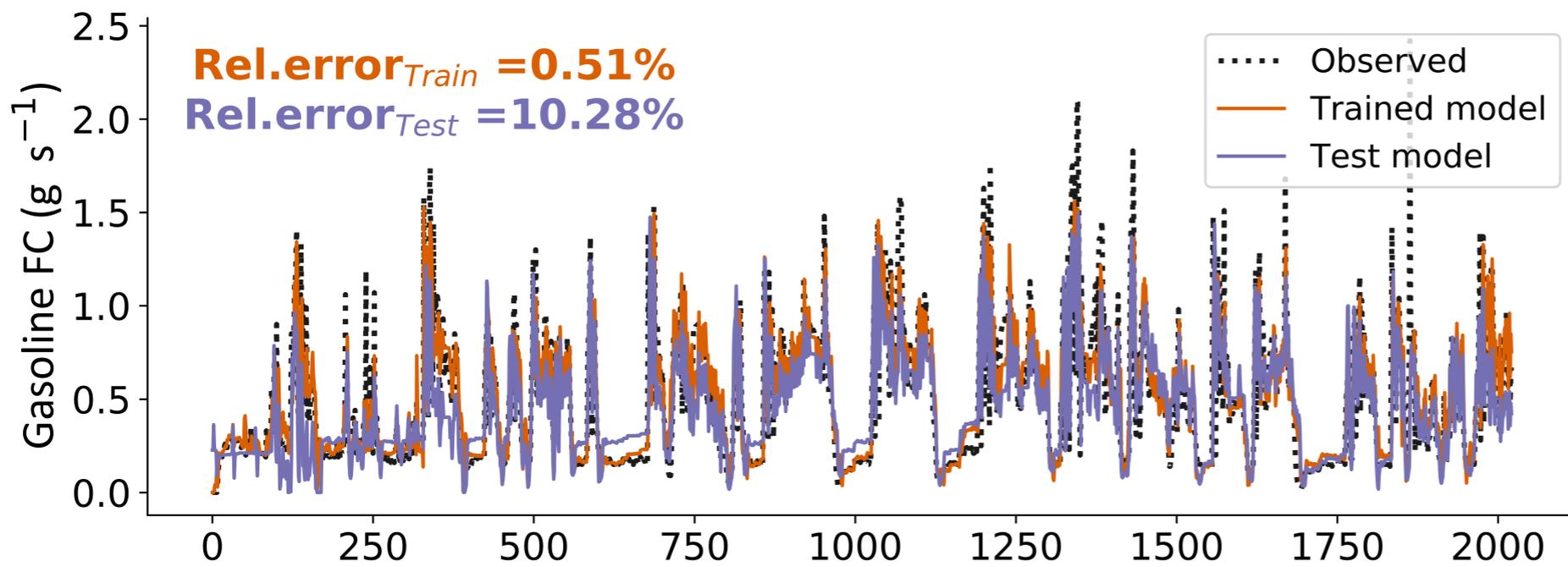


❖ **>80% of the CO, HC, and NO<sub>x</sub> were emitted in the first 8 min for gasoline vehicle** → cold start

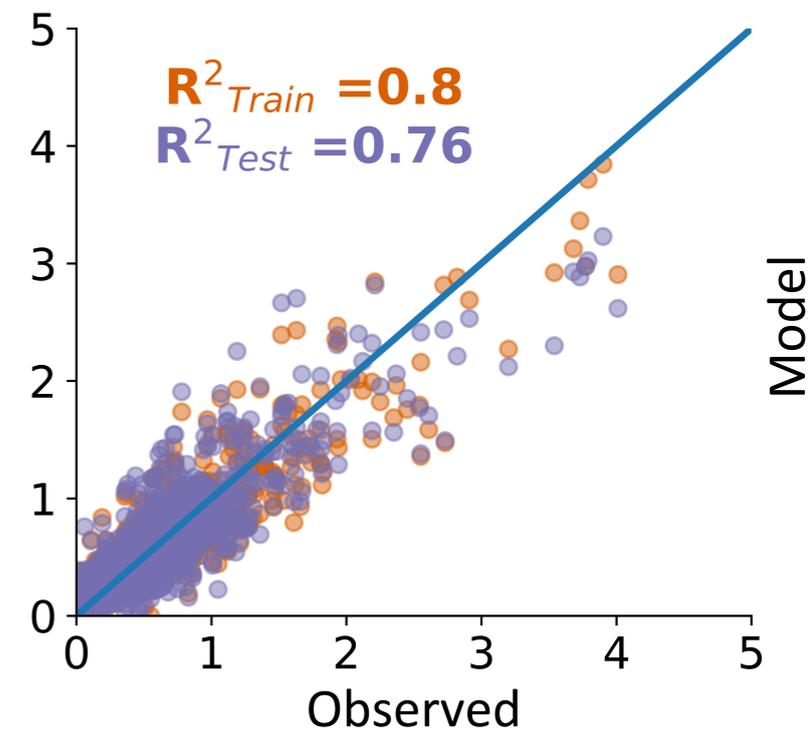
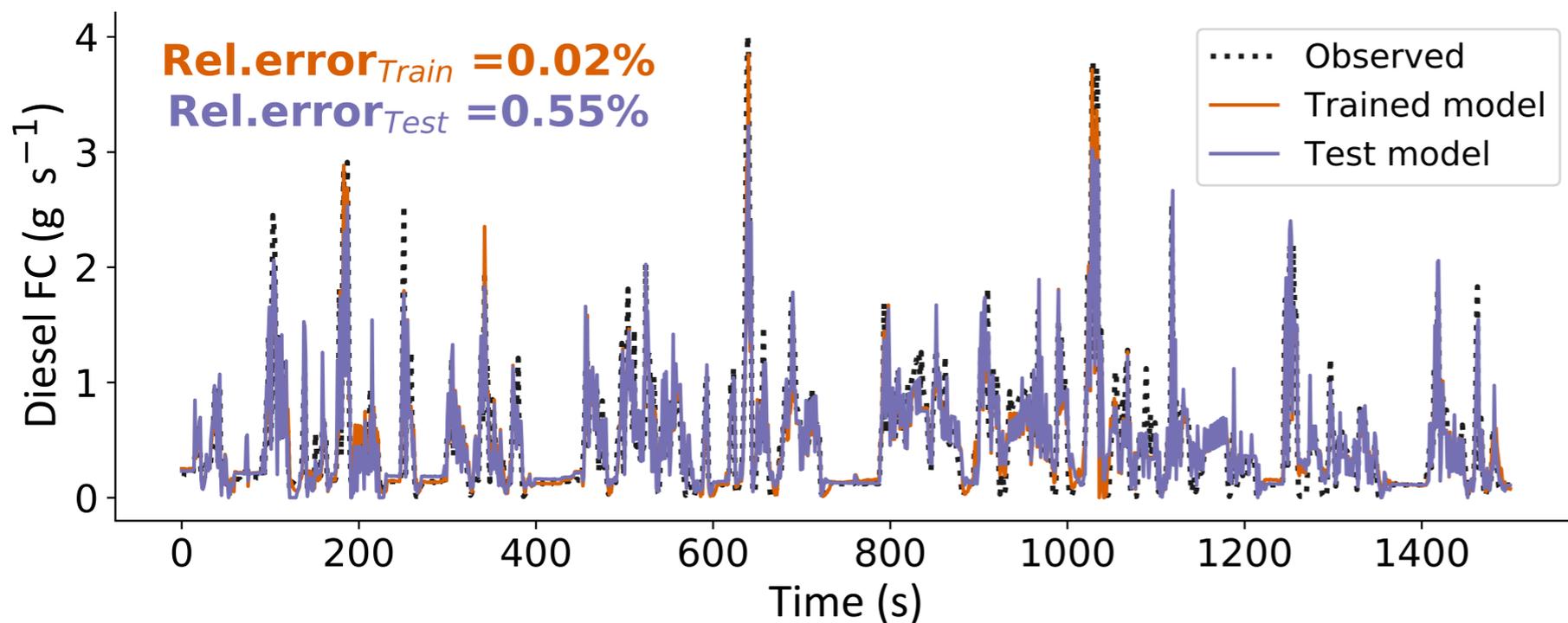
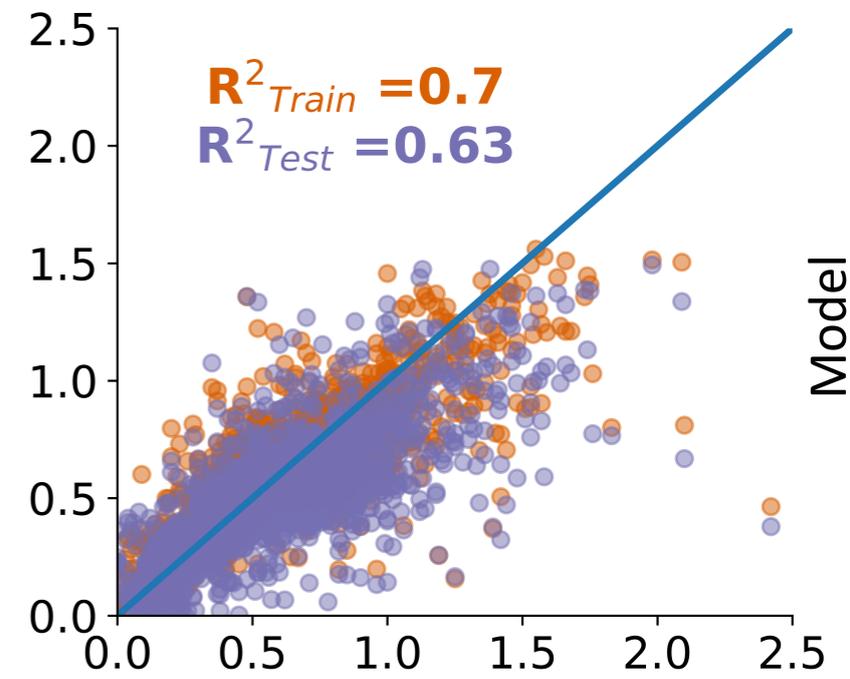
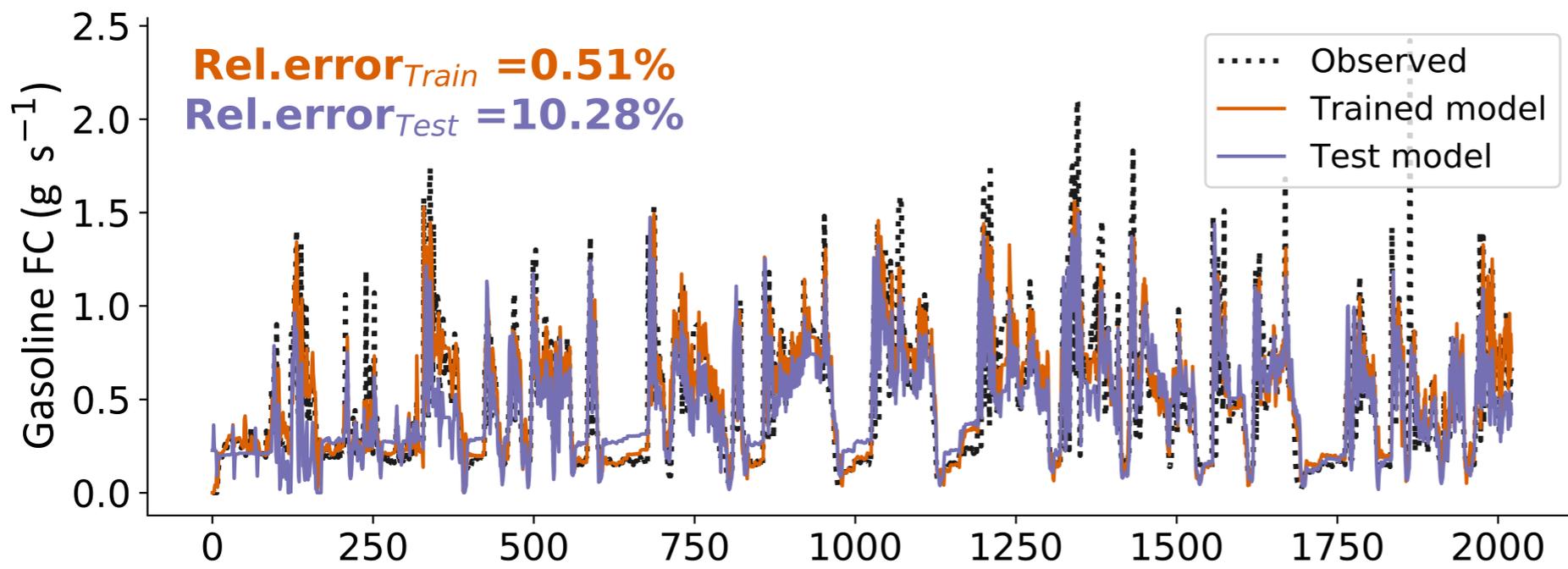
❖ Except CO, the diesel vehicle emissions were distributed over the entire route



- ❖ **ANN models train and test well in predicting instantaneous and cumulative fuel consumption**
- ❖ Performance better for diesel ( $RE=0.55\%$ ,  $R^2=0.76$ ) than gasoline ( $RE=10.3\%$ ,  $R^2=0.63$ )



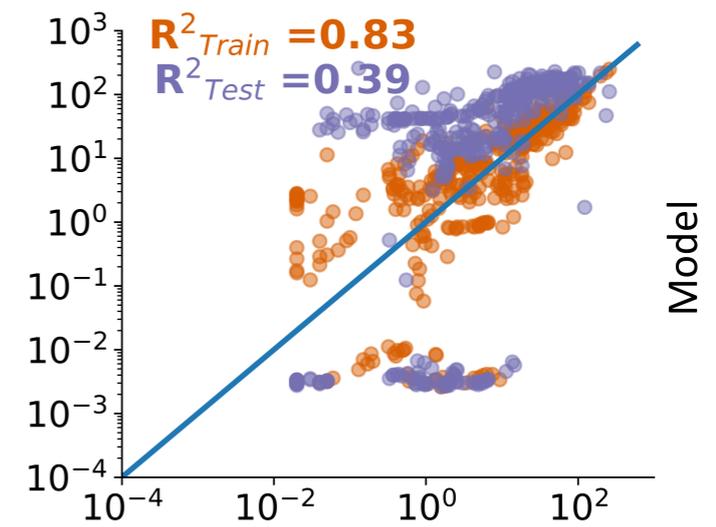
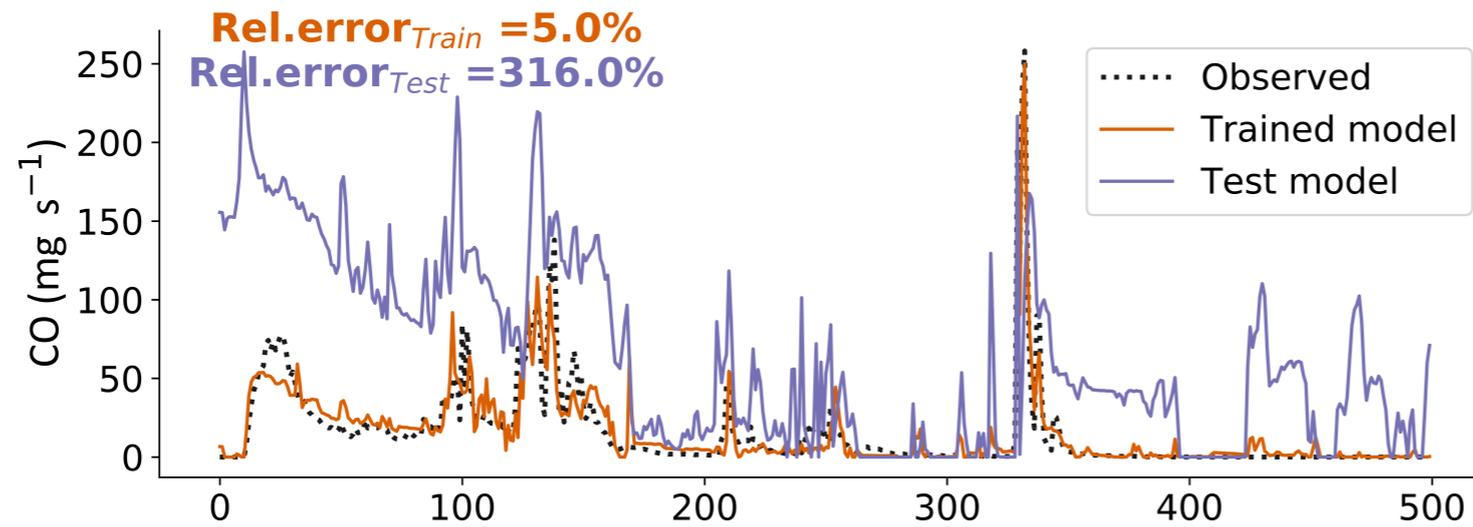
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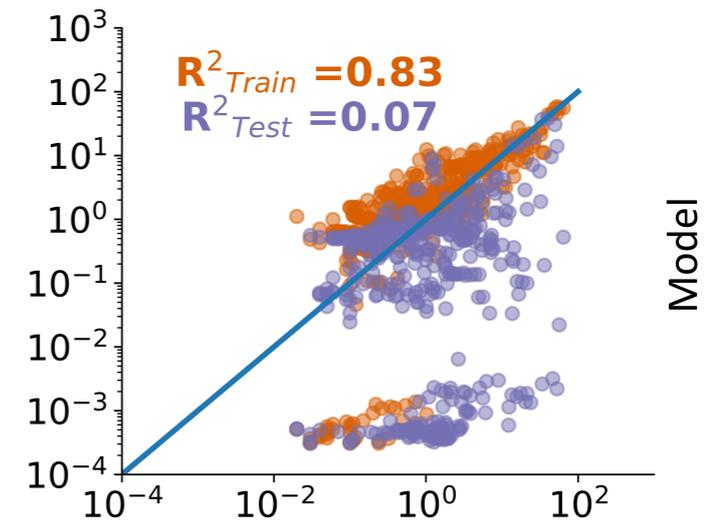
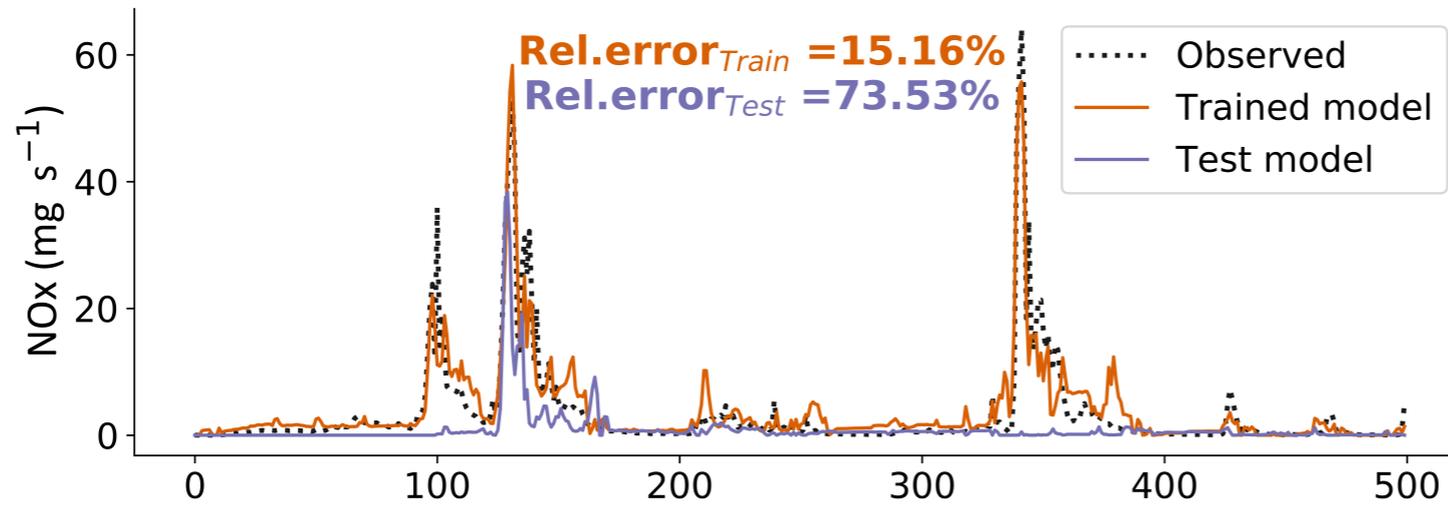
❖ For gasoline CO, NO<sub>x</sub>, and PM, ANN models

***trained well but did not test well ( $RE > 73\%$ ,  $R^2 < 0.4$ )***

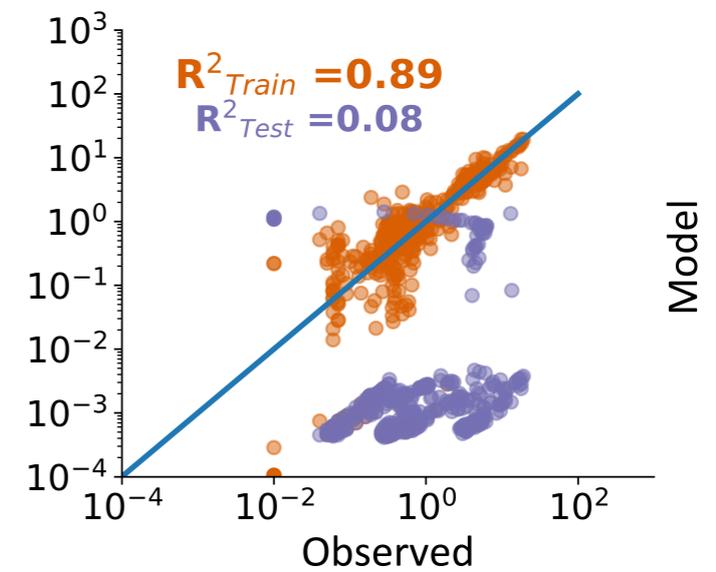
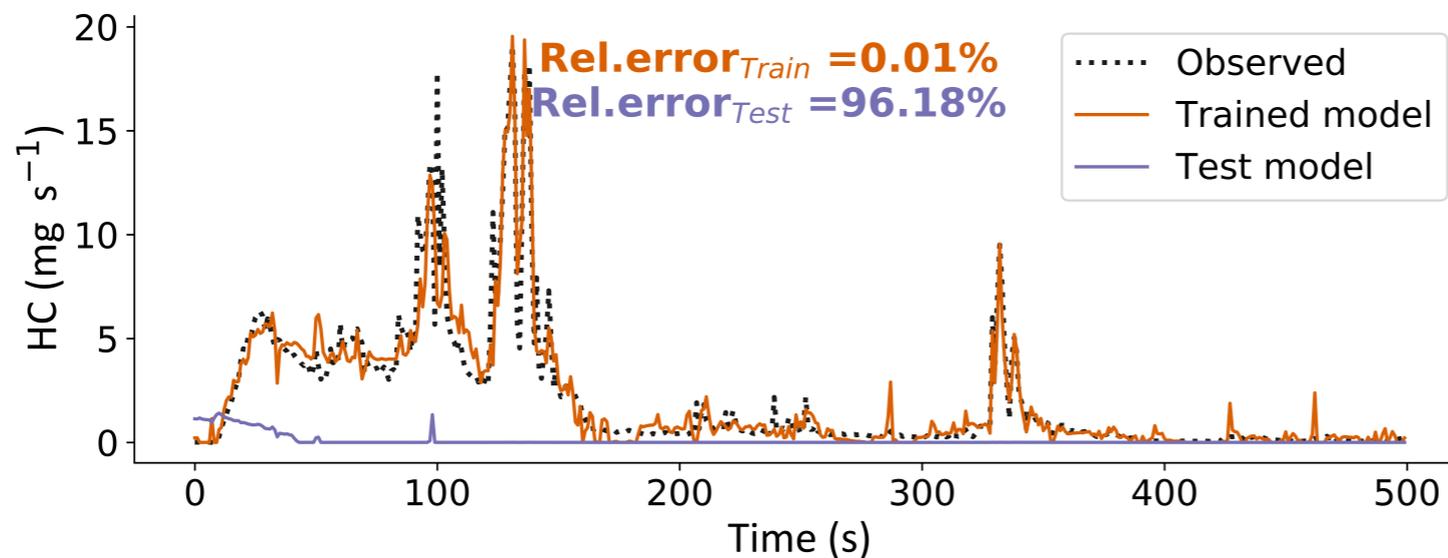
**CO**



**NO<sub>x</sub>**

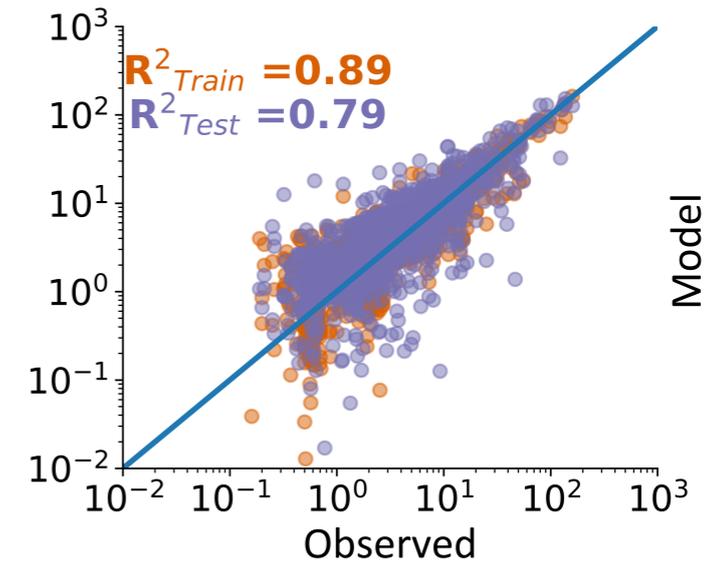
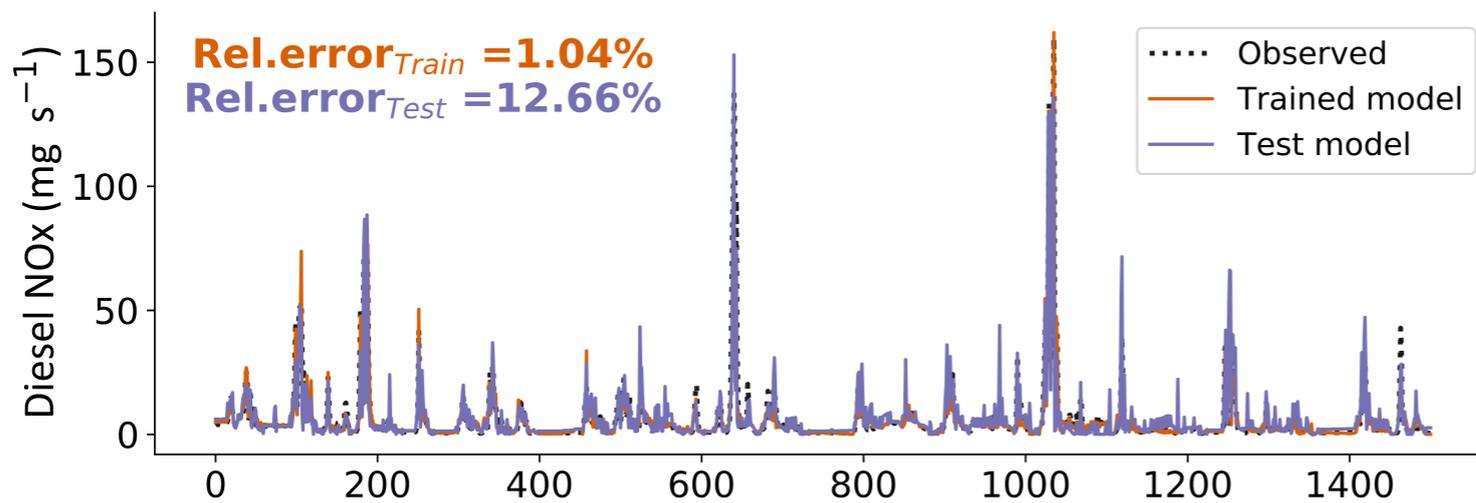


**HC**

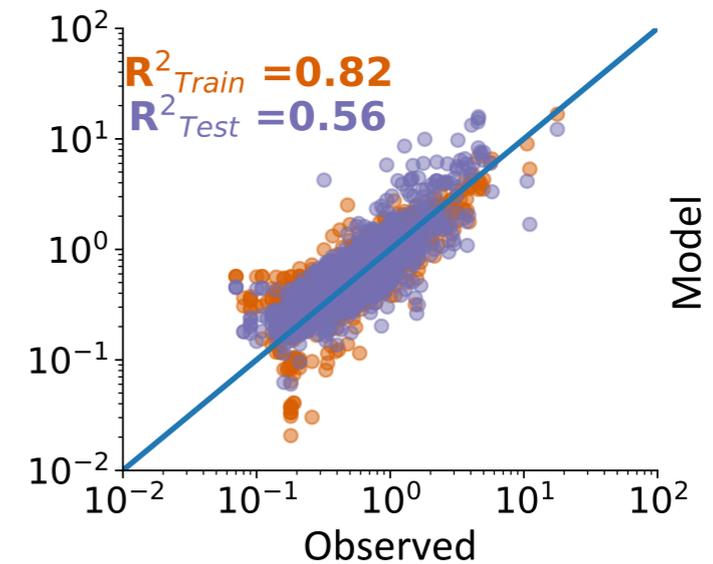
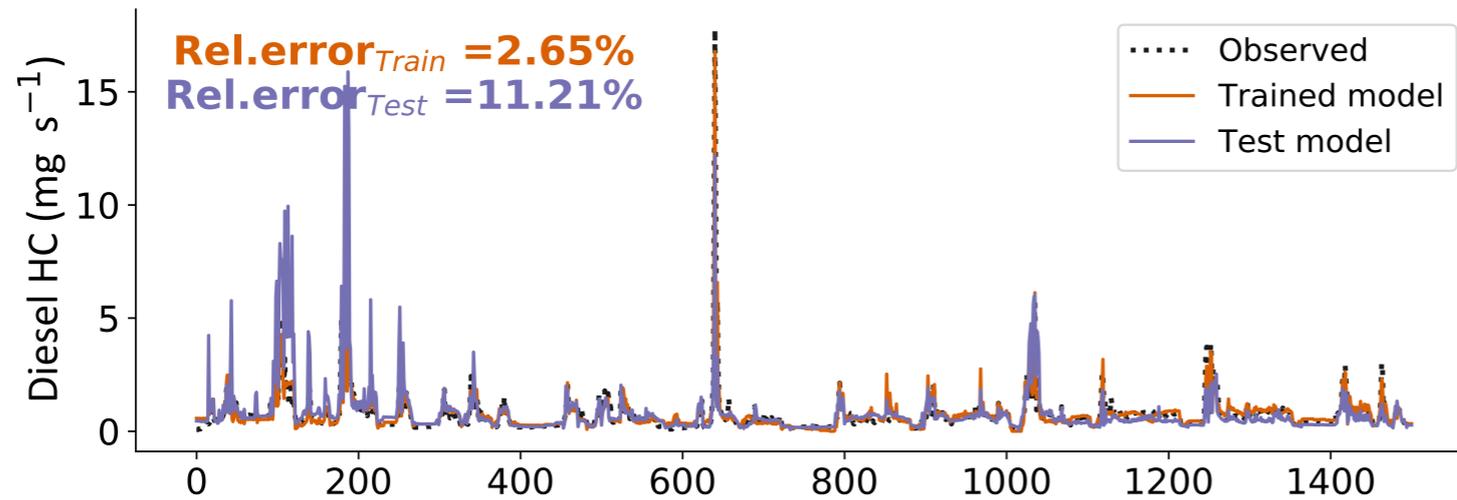


❖ In contrast, for diesel NO<sub>x</sub>, HC, and PM, ANN models **trained and tested well ( $RE < 16\%$ ,  $R^2 > 0.56$ )**

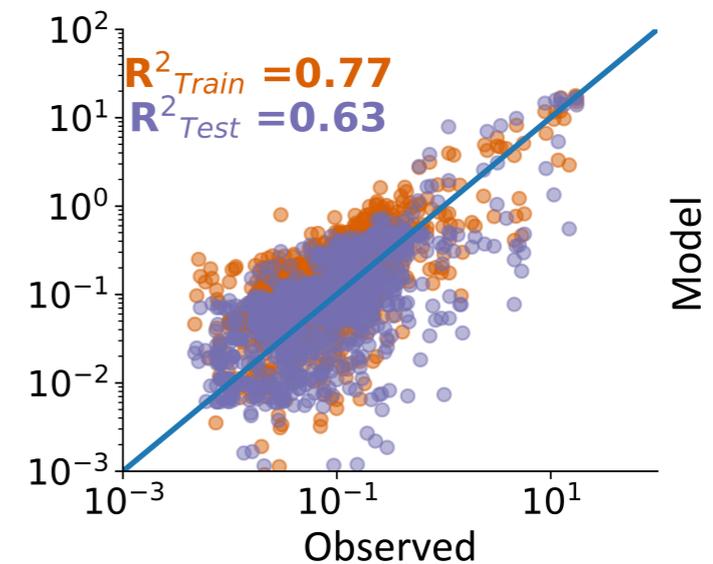
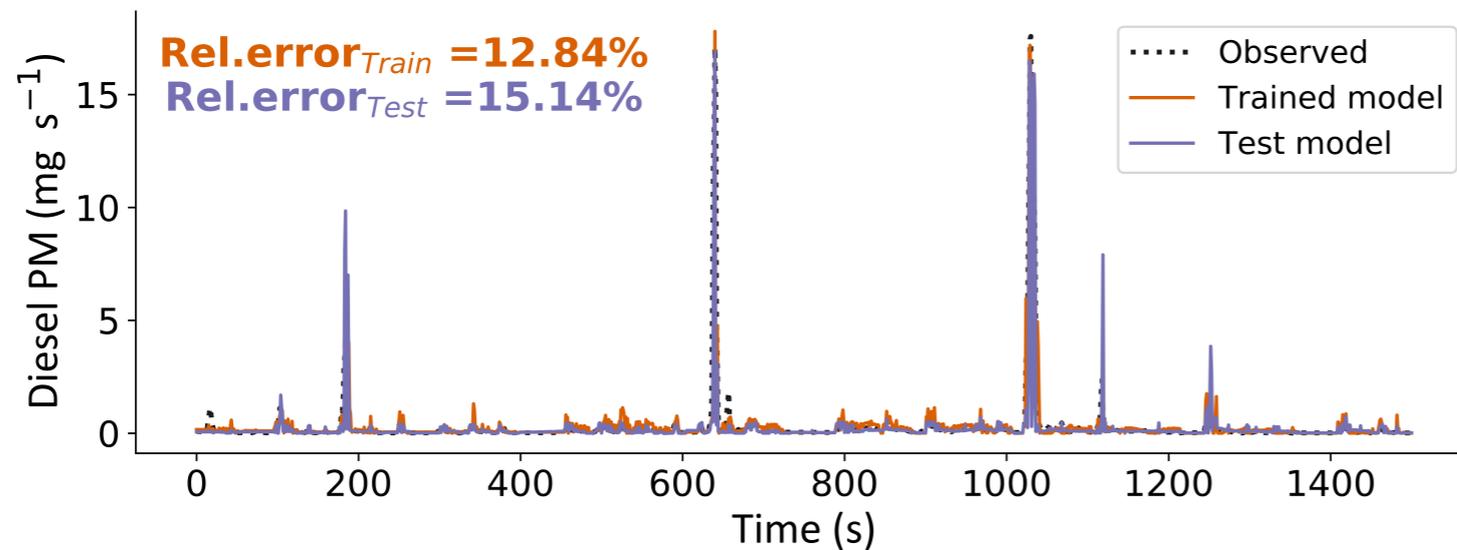
**NO<sub>x</sub>**



**HC**

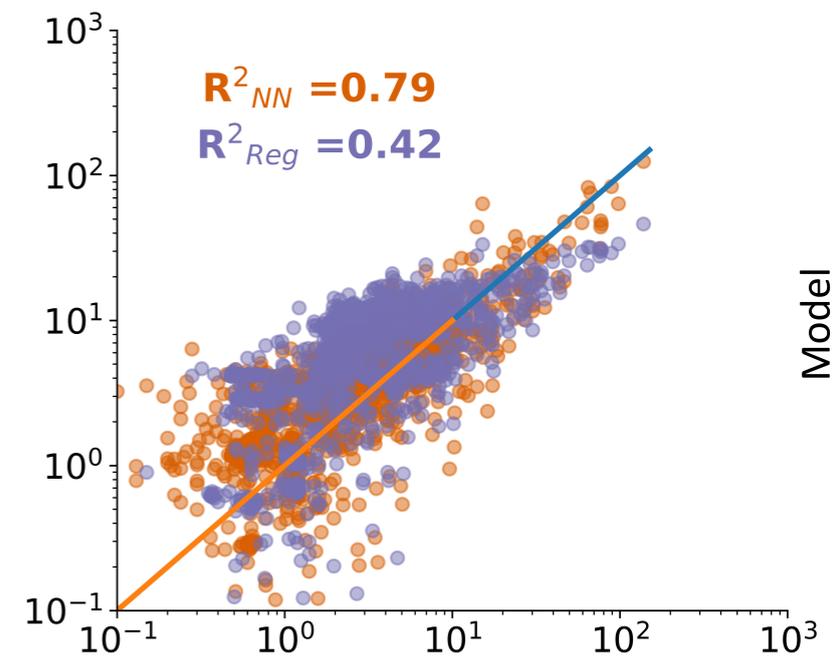
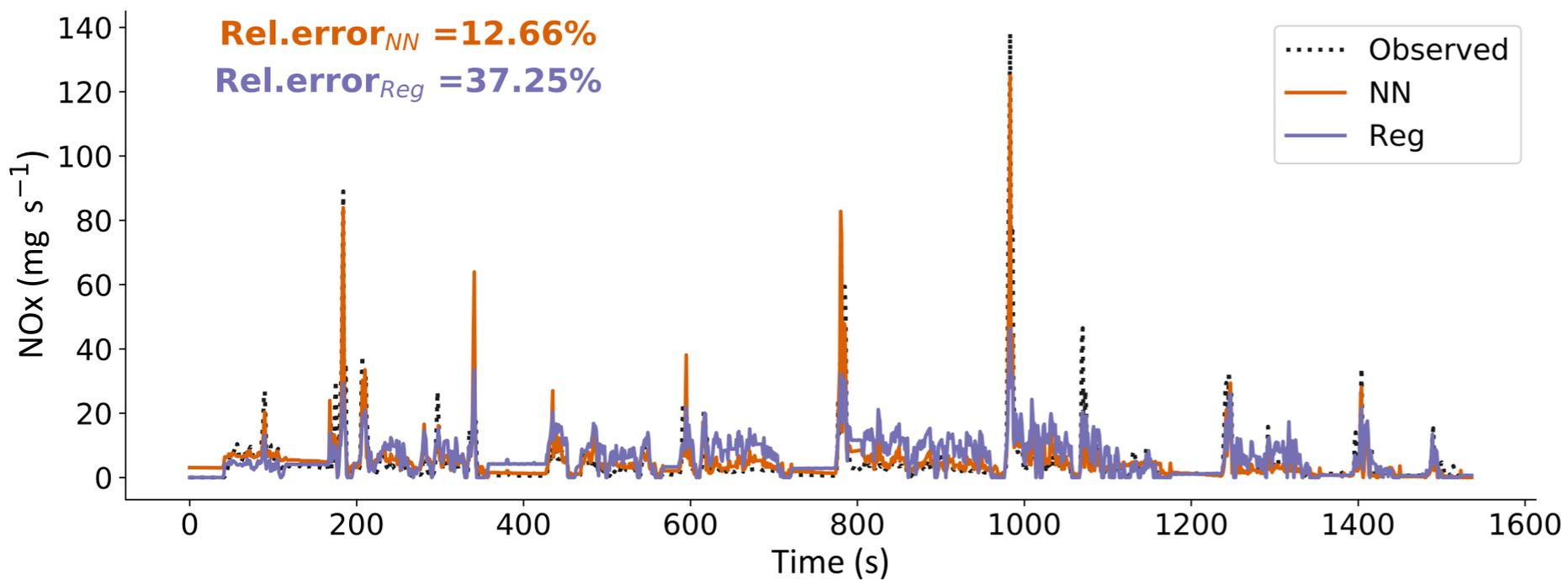
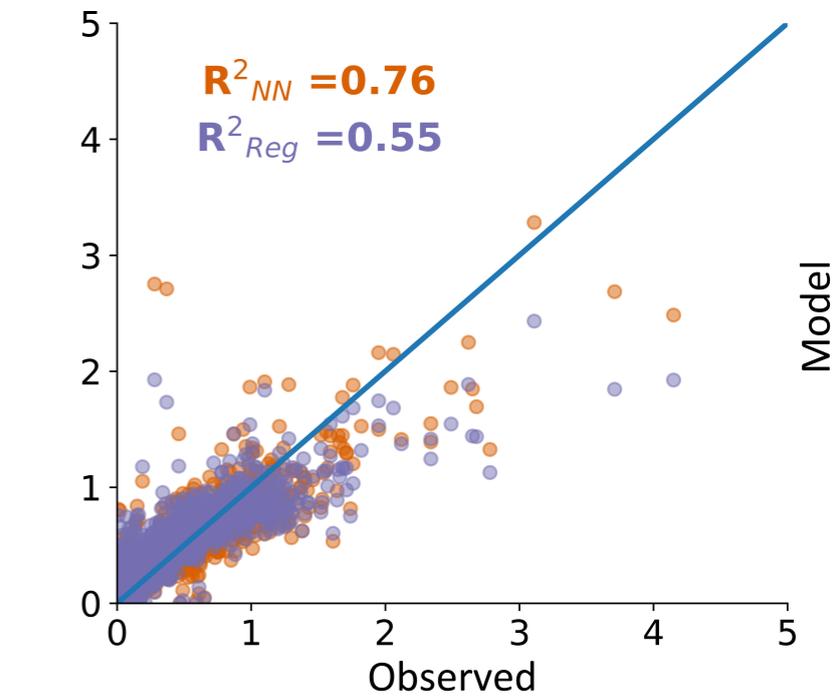
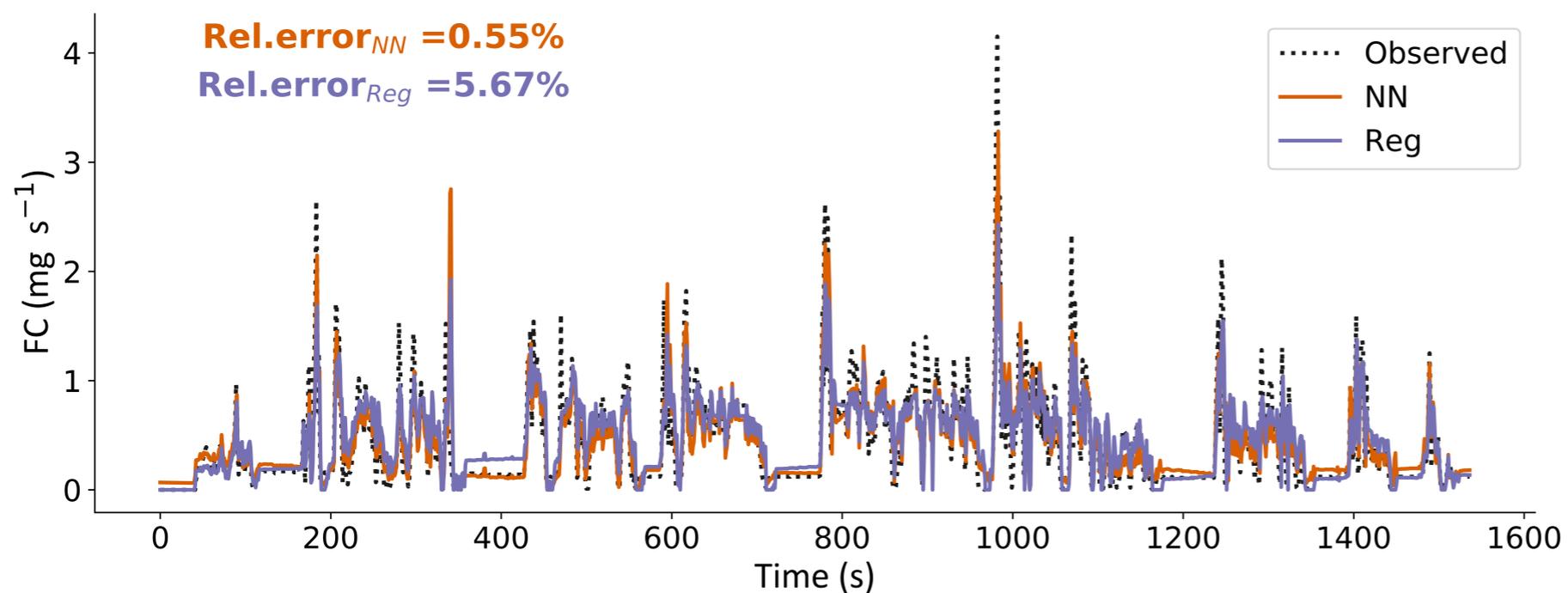


**PM**



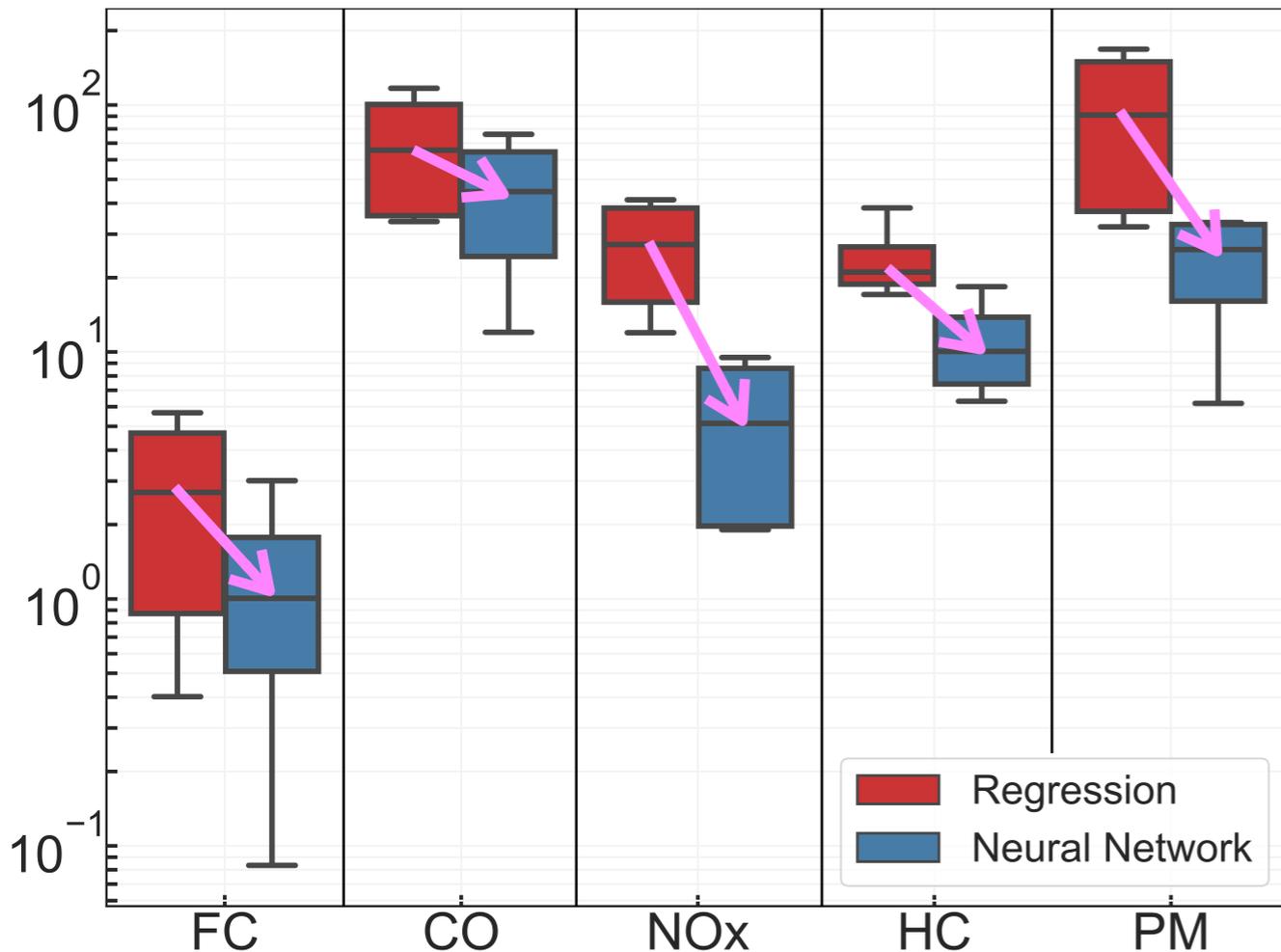
# ❖ ANN models perform better than multivariate regression models for diesel fuel consumption (RE=0.55 vs. 5.7%) and NO<sub>x</sub> (RE=12.7 vs. 37.2%)

Diesel FC and NO<sub>x</sub> - Regression vs NN Comparison

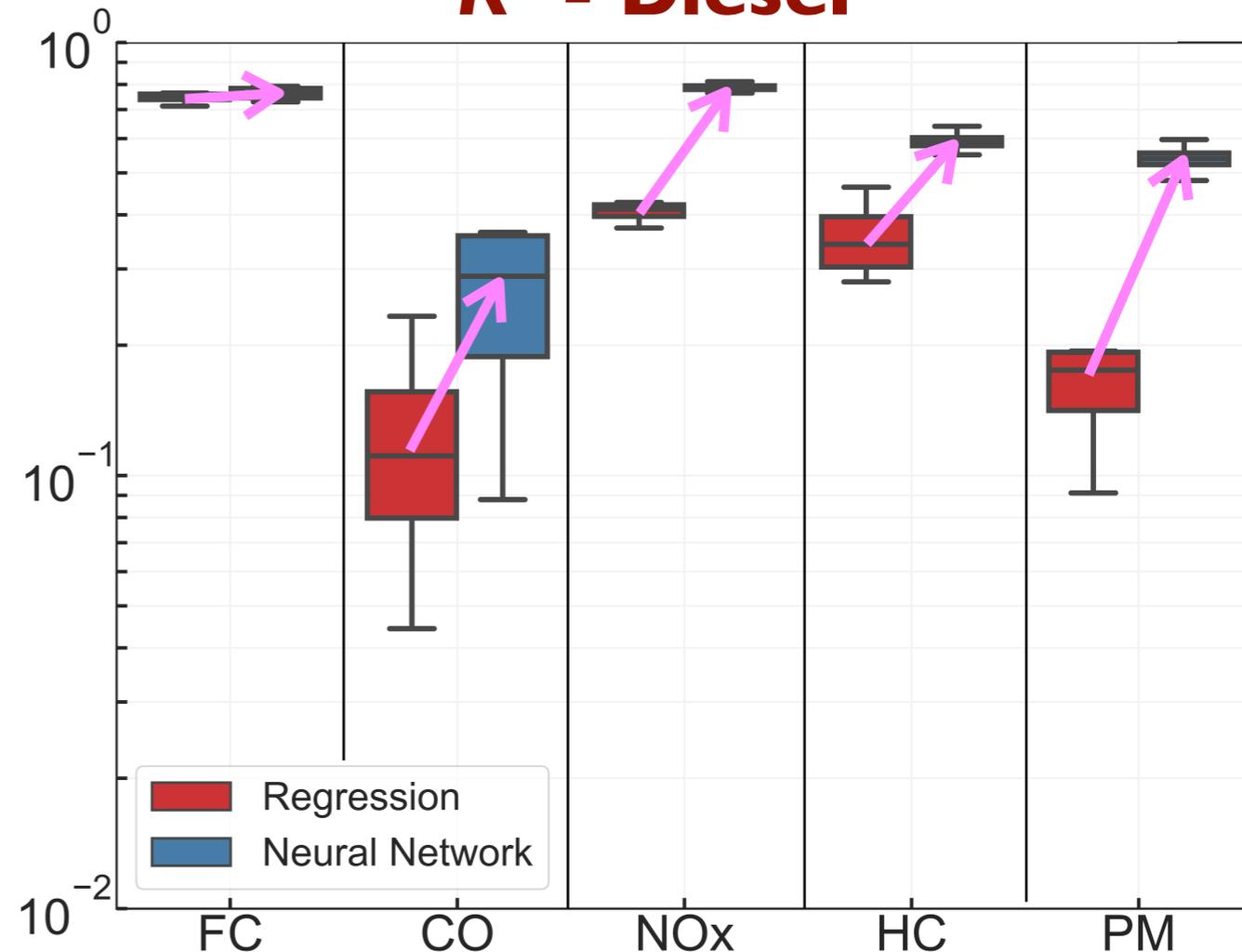


- ❖ **Overall, ANN models perform better (lower RE, higher  $R^2$ ) than multivariate regression models**
- ❖ For diesel, route fuel consumption and  $\text{NO}_x$  emissions were predicted within 3 and 10% respectively, with  $R^2 > 0.7$

**Relative Error (%) - Diesel**



**$R^2$  - Diesel**

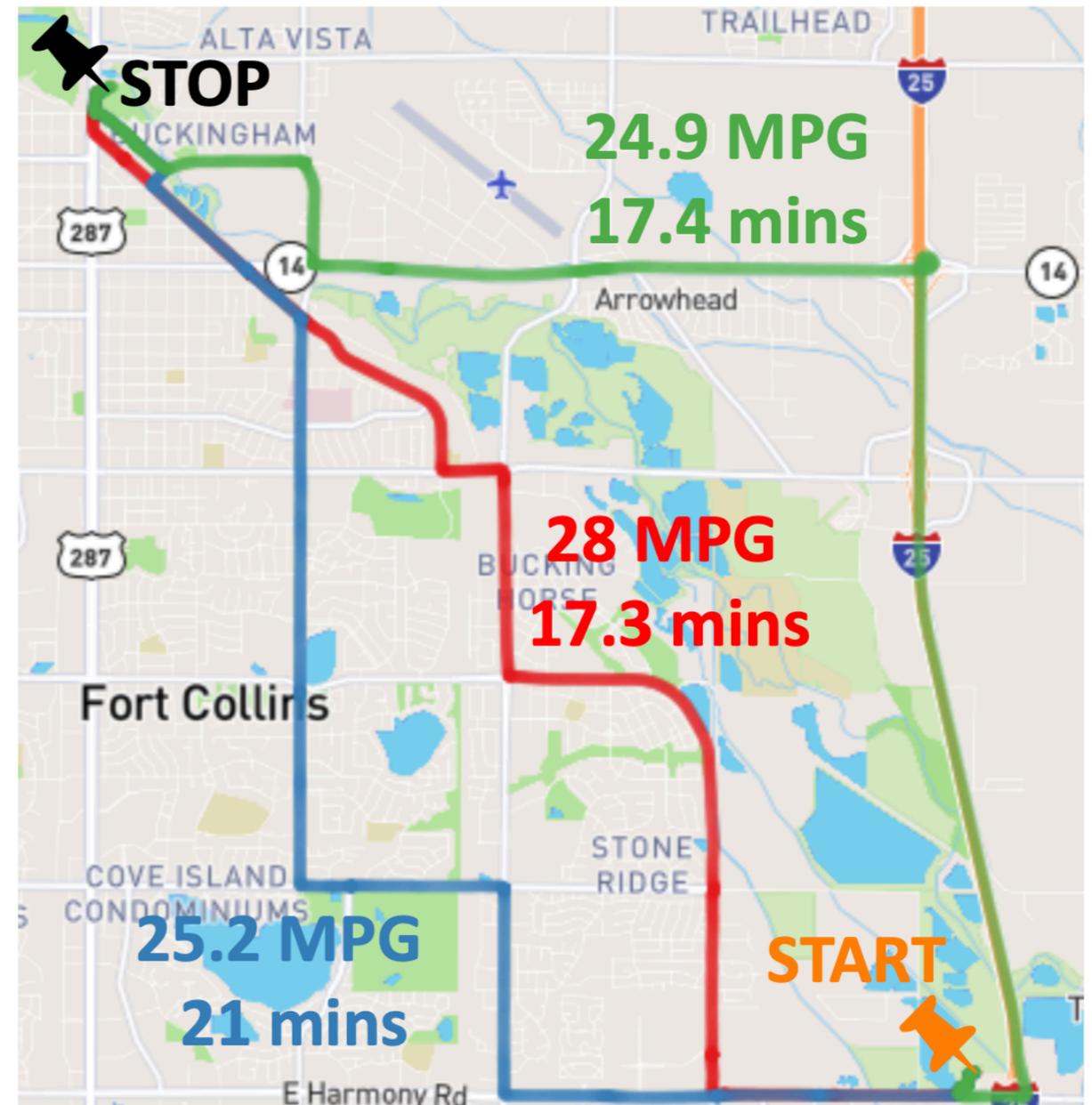
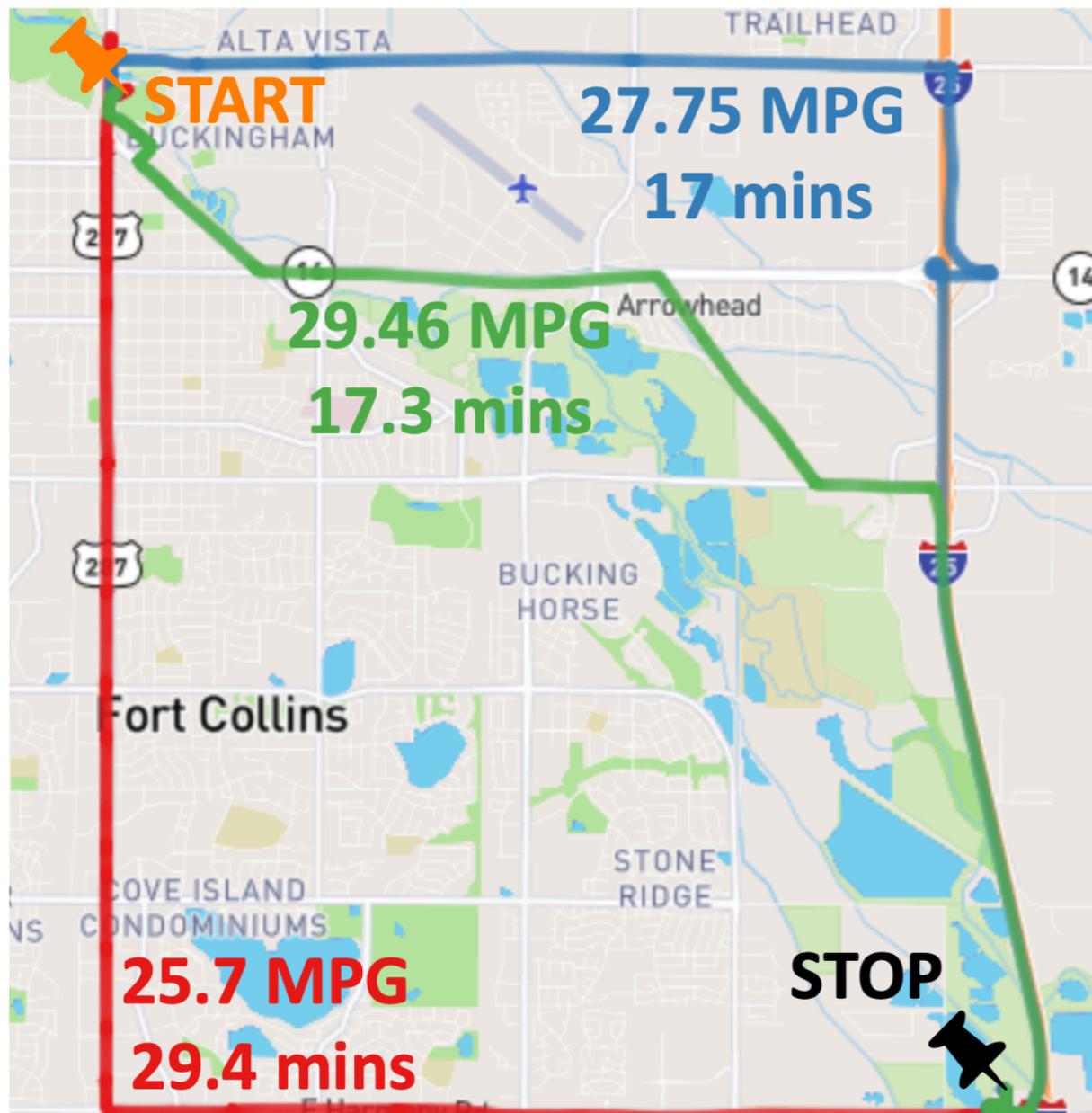


**❖ Most comprehensive model, unsurprisingly, yields the lowest RE and highest R<sup>2</sup>**

Model Number	Model Inputs	Gasoline FC		Diesel FC	
		RE	R <sup>2</sup>	RE	R <sup>2</sup>
M1	V	6.52	0.19	10.03	0.17
M2	VSP	8.16	0.60	1.19	0.63
M3	VSP, t	7.54	0.60	6.95	0.65
M4	V, VSP	4.30	0.65	0.58	0.70
M5	V, ACC	6.11	0.68	0.71	0.72
M6	V, VSP, t	4.15	0.65	1.63	0.69
M7	V, RPM, VSP	3.10	0.72	3.98	0.74
M8	V, ACC, t	4.68	0.69	0.23	0.74
M9	V, V <sup>3</sup> , t	4.57	0.20	2.03	0.20
M10	V, V <sup>3</sup> , ACC*V, t	6.30	0.65	2.56	0.69
M11	V, V <sup>3</sup> , ACC*V, RPM, t	3.44	0.72	3.51	0.74
M12	V, V <sup>3</sup> , ACC*V, V*RPM, t	3.85	0.66	6.68	0.71
M13	V, RPM, ACC, ACC*V, IAT, t	7.57	0.67	4.75	0.73
<b>M14</b>	<b>V, RPM, ACC, ACC*V, IAT, VSP, t</b>	<b>3.12</b>	<b>0.73</b>	<b>1.14</b>	<b>0.76</b>

V=velocity, VSP=vehicle specific power, t=time from ignition, ACC=acceleration, RPM=engine speed, IAT=intake air temperature

❖ In a case study, we demonstrated the ability of our ANN model to choose routes that were optimized for time and fuel economy for the gasoline vehicle.



# *Take-aways*

- ❖ ANN models were able to predict fuel consumption for the gasoline and diesel vehicle. For the diesel, the predicted route fuel consumption was always within 3% of the observed values.
- ❖ ANNs able to predict tailpipe emissions for the diesel vehicle but performance varied between pollutants, with the best predictions for NO<sub>x</sub> (within 10%).
- ❖ ANNs seemed to do better than multivariate regression models in capturing the non-linear processes.
- ❖ With access to velocity estimates and ambient data, ANNs could help optimize routing for fuel consumption and/or tailpipe emissions.

# Ongoing Work

- ❖ More PEMS tests in Spring 2019 with same vehicles
  - how well do models developed in 2018 perform for data in 2019?
- ❖ Model error propagation
  - how does uncertainty in an input (e.g., velocity) translate to an uncertainty in the output (e.g., fuel consumption)?
- ❖ Contact: **[shiva.chenna@colostate.edu](mailto:shiva.chenna@colostate.edu) or [shantanu.jathar@colostate.edu](mailto:shantanu.jathar@colostate.edu)**

Thank you | Questions?

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